1. Consider the following functions:

• $f: \mathbb{R} \to \mathbb{R}, f(x) = x^2 + x$

• $f: \mathbb{R} \to \mathbb{R}, f(x) = 2x$

• $f: \mathbb{R} \to \mathbb{R}, f(x) = x - 3$

• $g: \mathbb{R}^2 \to \mathbb{R}^2$, $g(x,y) = (x,y^2)$

• $g: \mathbb{R}^2 \to \mathbb{R}^2$, $g(x,y) = (x^3, y)$

• $g: \mathbb{R}^2 \to \mathbb{R}^2$, g(x,y) = (5x,2y)

• $g: \mathbb{R}^2 \to \mathbb{R}^2, \ g(x,y) = (-x, -y)$

- (a) Which of these mappings are transformations? Justify your answer.
- (b) Which of these mappings are affine transformations? Justify your answer.
- (c) Which of these mappings are isometries? Justify your answer.

2. Prove each of the following:

- (a) The inverse of a transformation is a transformation.
- (b) The inverse of an isometry is an isometry.
- (c) The set of all transformations of a plane forms a group under the operation function composition.
- (d) Given f, an isometry of \mathbb{E} and a triangle $\triangle ABC$, if f(A) = A', f(B) = B', and f(C) = C', then $\triangle ABC \cong \triangle A'B'C'$.
- 3. (a) Find homogeneous coordinates for the line $\ell[l_1, l_2, l_3]$ containing the points (-3, 1, 1) and (1, -2, 1).
 - (b) Find the point of intersection of the lines [4, -1, 0] and [3, 2, -10].
 - (c) Find the angle between the lines [4, -1, 0] and [3, 2, -10].

4. Define each of the following terms:

- (a) a transformation of a plane.
- (b) an isometry.
- (c) a group.
- (d) a reflection.
- (e) a translation.
- 5. (a) Find the matrix for the transformation T_{PQ} given:

i.
$$P(2,3,1), Q(5,3,1)$$

ii.
$$P(2,3,1), Q(-1,5,1)$$

(b) Find the matrix for the transformation $R_{C,\theta}$ given:

i.
$$C(0,0,1)$$
 and $\theta = 135^{\circ}$

ii.
$$C(-1, 2, 1)$$
 and $\theta = 30^{\circ}$

(c) Find the matrix for R_{ℓ} given:

i.
$$\ell[100]$$

ii.
$$\ell[111]$$

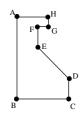
- (d) Find the matrix for G_{PQ} given P(2,3,1) and Q(3,3,1).
- 6. For each statement, determine whether the statement is true or false. Then briefly justify your answer.
 - (a) Every isometry of \mathbb{E} is a translation, a rotation, or a reflection.
 - (b) The product of any two distinct rotations is a translation.
 - (c) A nontrivial translation has no invariant points.

- (d) A nontrivial rotation has exactly one invariant point.
- (e) A nontrivial translation has no invariant lines.
- (f) A nontrivial rotation has no invariant lines.
- (g) A nontrivial reflection has exactly one invariant line.
- 7. Let f be the transformation given by the matrix $A = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix}$
 - (a) Find the image of the points P(1,3,1) and Q(-2,5,1) under this transformation.
 - (b) Find the image of the line [1-24] under this transformation.
 - (c) What transformation is this?.
- 8. Given the points P(2,1,1) and Q(4,2,1)
 - (a) Find the matrix of a translation that maps P to Q.
 - (b) Find the matrix of a reflection that maps P to Q.
 - (c) Find the matrix of a rotation that maps P to Q.
- 9. Consider the following transformation matrices:

$$A = \begin{bmatrix} 1 & 2 & 1 \\ 3 & 0 & -1 \\ 2 & 1 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 & -1 & 3 \\ 2 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \quad C = \begin{bmatrix} 1 & 0 & -5 \\ 0 & -1 & 3 \\ 0 & 0 & 1 \end{bmatrix}$$

$$D = \begin{bmatrix} 0 & 1 & 3 \\ 1 & 0 & -1 \\ 0 & 0 & 1 \end{bmatrix} \quad E = \begin{bmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} & 0 \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad F = \begin{bmatrix} 1 & 0 & -5 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{bmatrix}$$

- (a) Which of these are the the matrix of an affine transformation of \mathbb{E} ?
- (b) Which of these are the the matrix of an isometry of \mathbb{E} ?
- (c) Which of these are the the matrix of an direct isometry of \mathbb{E} ?
- (d) Which of these are the the matrix of a rotation of \mathbb{E} ?
- (e) Which of these are the the matrix of a translation of \mathbb{E} ?
- 10. Given the plane figure in E shown below, accurately draw the image of this figure under each of the following isometries:



- (a) $R_{B,90}$
- (b) T_{FG}
- (c) R_{ℓ} , where $\ell = \overleftrightarrow{HG}$.
- (d) R_{ℓ} , where $\ell = \overleftrightarrow{ED}$.
- (e) G_{CD}

- 11. Prove or Disprove:
 - (a) The set of all translations of \mathbb{E} forms a group under composition.
 - (b) The set of all rotations of \mathbb{E} forms a group under composition.
 - (c) The set of all *indirect isometries* of \mathbb{E} forms a group under composition.
- 12. Let $\Box ABCD$ be the unit square centered at the origin in \mathbb{E} .
 - (a) Give a complete list of all of the symmetries of $\Box ABCD$.
 - (b) Show that the set of isometries that you found in part (a) forms a group under composition.