1. Consider the following functions:

•  $f: \mathbb{R} \to \mathbb{R}, f(x) = x^2 + x$ 

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$$f: \mathbb{R} \to \mathbb{R}, f(x) = 2x$$

- $f : \mathbb{R} \to \mathbb{R}, f(x) = x 3$
- $g: \mathbb{R}^2 \to \mathbb{R}^2, g(x, y) = (x, y^2)$

- $g: \mathbb{R}^2 \to \mathbb{R}^2, \ g(x,y) = (x^3,y)$
- $g: \mathbb{R}^2 \to \mathbb{R}^2, \ g(x,y) = (5x,2y)$
- $g: \mathbb{R}^2 \to \mathbb{R}^2, g(x, y) = (-x, -y)$
- (a) Which of these mappings are transformations? Justify your answer.
- (b) Which of these mappings are affine transformations? Justify your answer.
- (c) Which of these mappings are isometries? Justify your answer.
- 2. Prove each of the following:
  - (a) The inverse of a transformation is a transformation.
  - (b) The inverse of an isometry is an isometry.
  - (c) The set of all transformations of a plane forms a group under the operation function composition.
  - (d) Given f, an isometry of  $\mathbb{E}$  and a triangle  $\triangle ABC$ , if f(A) = A', f(B) = B', and f(C) = C', then  $\triangle ABC \cong \triangle A'B'C'$ .
- 3. (a) Find homogeneous coordinates for the line  $\ell[l_1, l_2, l_3]$  containing the points (-3, 1, 1) and (1, -2, 1).
  - (b) Find the point of intersection of the lines [4, -1, 0] and [3, 2, -10].
  - (c) Find the angle between the lines [4, -1, 0] and [3, 2, -10].
- 4. Define each of the following terms:
  - (a) a transformation of a plane.
  - (b) an isometry.
  - (c) a group.
  - (d) a reflection.
  - (e) a translation.
- 5. (a) Find the matrix for the transformation  $T_{PQ}$  given:
  - i. P(2,3,1), Q(5,3,1) ii. P(2,3,1), Q(-1,5,1)
  - (b) Find the matrix for the transformation  $R_{C,\theta}$  given:

i. C(0,0,1) and  $\theta = 135^{\circ}$  ii. C(-1,2,1) and  $\theta = 30^{\circ}$ 

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- (c) Find the matrix for  $R_{\ell}$  given:
  - i.  $\ell[100]$
- (d) Find the matrix for  $G_{PQ}$  given P(2,3,1) and Q(3,3,1).
- 6. For each statement, determine whether the statement is true or false. Then briefly justify your answer.
  - (a) Every isometry of  $\mathbb{E}$  is a translation, a rotation, or a reflection.
  - (b) The product of any two distinct rotations is a translation.
  - (c) A nontrivial translation has no invariant points.
  - (d) A nontrivial rotation has exactly one invariant point.
  - (e) A nontrivial translation has no invariant lines.
  - (f) A nontrivial rotation has no invariant lines.
  - (g) A nontrivial reflection has exactly one invariant line.

- 7. Let f be the transformation given by the matrix  $A = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix}$ 
  - (a) Find the image of the points P(1,3,1) and Q(-2,5,1) under this transformation.
  - (b) Find the image of the line [1 24] under this transformation.
  - (c) What transformation is this?.

8. Given the points P(2, 1, 1) and Q(4, 2, 1)

- (a) Find the matrix of a *translation* that maps P to Q.
- (b) Find the matrix of a *reflection* that maps P to Q.
- (c) Find the matrix of a *rotation* that maps P to Q.

9. Consider the following transformation matrices:

$$A = \begin{bmatrix} 1 & 2 & 1 \\ 3 & 0 & -1 \\ 2 & 1 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 & -1 & 3 \\ 2 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \quad C = \begin{bmatrix} 1 & 0 & -5 \\ 0 & -1 & 3 \\ 0 & 0 & 1 \end{bmatrix}$$

$$D = \begin{bmatrix} 0 & 1 & 3 \\ 1 & 0 & -1 \\ 0 & 0 & 1 \end{bmatrix} \quad E = \begin{bmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} & 0 \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad F = \begin{bmatrix} 1 & 0 & -5 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{bmatrix}$$

- (a) Which of these are the the matrix of an affine transformation of  $\mathbb{E}$ ?
- (b) Which of these are the the matrix of an isometry of  $\mathbb{E}$ ?
- (c) Which of these are the the matrix of an direct isometry of  $\mathbb{E}$ ?
- (d) Which of these are the the matrix of a rotation of  $\mathbb{E}$ ?
- (e) Which of these are the matrix of a translation of  $\mathbb{E}$ ?

10. Given the plane figure in  $\mathbb{E}$  shown below, accurately draw the image of this figure under each of the following isometries:



11. Prove or Disprove:

- (a) The set of all *translations* of  $\mathbb{E}$  forms a group under composition.
- (b) The set of all *rotations* of  $\mathbb{E}$  forms a group under composition.
- (c) The set of all *indirect isometries* of  $\mathbb{E}$  forms a group under composition.

12. Let  $\Box ABCD$  be the unit square centered at the origin in  $\mathbb{E}$ .

- (a) Give a complete list of all of the symmetries of  $\Box ABCD$ .
- (b) Show that the set of isometries that you found in part (a) forms a group under composition.