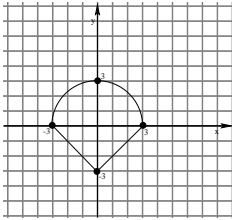


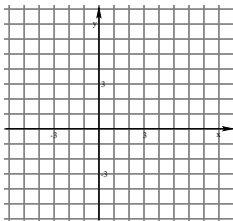
### Transformational Geometry

In Chapter 2, we looked exclusively at static objects (objects that are fixed in one position). In this chapter, we will take a more dynamic approach. We will consider the idea of moving one object onto another similar object. The concept of a transformation is a function that maps a set onto another set. In some sense, motion is introduced using one-to-one and onto functions, called transformations.

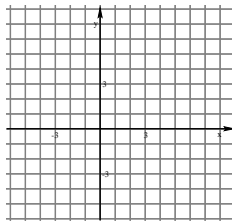
1. Draw the result after performing each indicated transformation on the figure given below.



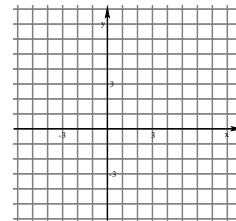
(a) Rotation  $90^\circ$  Counterclockwise



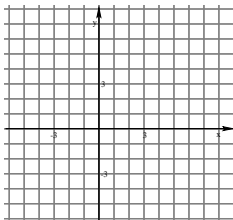
(b) Rotation by  $180^\circ$



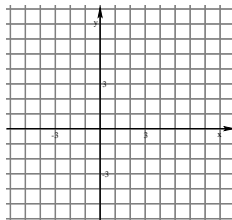
(c) Reflection across the  $x$ -axis



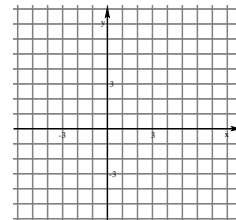
(d) Reflection across the  $y$ -axis



(e) Translation by the vector  $\langle 3, 0 \rangle$



(f) Translation by the vector  $\langle -2, 2 \rangle$



#### Definitions:

- A **mapping** (or function  $f : A \rightarrow B$ ) of a set  $A$  into a set  $B$  is a rule that pairs each element of  $A$  with exactly one element of a subset of  $B$ . The set  $A$  is called the **domain**, the set  $B$  is called the **co-domain**, and the set of all elements of  $B$  (a subset of  $B$ ) that are paired with an element from  $A$  is called the **range**.
- A mapping  $f$  from  $A$  to  $B$  is **onto**  $B$  if for any  $b \in B$  there is at least one  $a \in A$  such that  $f(a) = b$ .
- A mapping  $f : A \rightarrow B$  is **one-to-one** if each element of the range of  $f$  is the image of exactly one element from  $A$ .
- A **transformation** is a one-to-one mapping of a set  $A$  onto a set  $B$ .
- A **transformation of a plane** is a transformation that maps points of the plane onto points in the plane.
- A nonempty set  $G$  is said to form a **group under a binary operation**  $\star$ , if it satisfies the following conditions:
  - If  $A$  and  $B$  are in  $G$ , then  $A \star B$  is in  $G$ . (The set is **closed** under the operation, **closure**.)
  - There exists an element  $I \in G$  such that for every element  $A \in G$ ,  $I \star A = A \star I = A$ . (The set has an **identity**.)
  - For every element  $A \in G$ , there is an element  $B \in G$  such that  $A \star B = B \star A = I$ , denoted  $A^{-1}$ . (Every element has an **inverse**.)
  - If  $A, B, C \in G$ , then  $(A \star B) \star C = A \star (B \star C)$ . (the operation  $\star$  is **associative**)

**Theorem 3.0:** The set of transformations of a plane is a group under composition.

**Proof Outline:** The result follows from the following:

- The composition of two transformations of a plane is a transformation (Exercise 3.4).
- The inverse of a transformation is a transformation (Exercise 3.5).
- The identity function is a transformation and composition of functions is associative (Exercise 3.5).

2. Determine whether or not the mapping  $f : \mathbb{R} \rightarrow \mathbb{R}$  given by  $f(x) = \frac{x-3}{2}$  is a transformation.

3. Determine whether or not the mapping  $f : \mathbb{R} \rightarrow \mathbb{R}$  given by  $f(x) = x^2$  is a transformation.

4. Determine whether or not the mapping  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  given by  $f(x, y) = (2x, 3y)$  is a transformation.

5. Prove the composition of two transformations of a plane is a transformation of the plane.

**Note:** The three parts of Exercise 3.5 (See 3.2.1 in your textbook) are presentation eligible problems for Friday in class.