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## 3.6.2 Similarity for the Analytic Euclidean Plane Model

I believe the geometric proportion served the creator as an idea when He introduces the continuous generation of similar objects from similar objects. — Johannes Kepler (1571–1630)

The matrix of an affine similarity may be found by a method that is analogous to the method used in determining the matrix of an <u>affine isometry</u>.

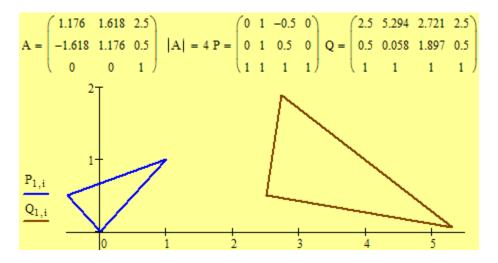
*Proposition 3.16. An affine transformation of the Euclidean plane is a <i>similarity* with ratio r if and only if the matrix representation is

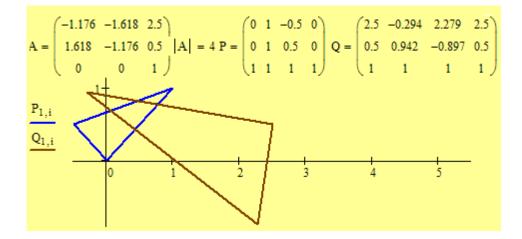
$$\begin{bmatrix} r\cos\theta & -r\sin\theta & a \\ r\sin\theta & r\cos\theta & b \\ 0 & 0 & 1 \end{bmatrix}$$
 (direct similarity)  
or 
$$\begin{bmatrix} r\cos\theta & r\sin\theta & a \\ r\sin\theta & -r\cos\theta & b \\ 0 & 0 & 1 \end{bmatrix}$$
 (indirect similarity)

Corollary to Proposition 3.16. The determinant of a direct similarity is  $r^2$  and the determinant of an indirect isometry is  $-r^2$ .

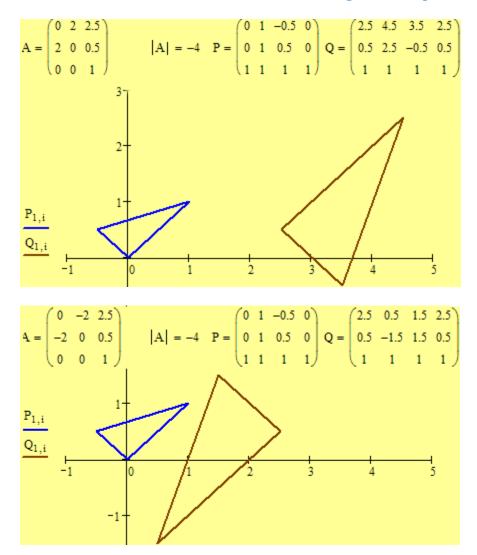
*Examples.* Which is a direct similarity? Which is an indirect similarity? Note the positions of the triangles.

Matrix A is the similarity matrix. Matrix P is the matrix of the three endpoints of the original triangle. Matrix Q = AP is the matrix of the transformed endpoints. **Click here to view an animation of the following two examples.** 





Click here to view an animation of the following two examples.



The matrix for an affine dilation may be found by following the procedures as with the other matrix derivations.

Proposition 3.17. An affine transformation of the Euclidean plane is a *dilation* with ratio r and center

$$\begin{bmatrix} r & 0 & c_1(1-r) \\ 0 & r & c_2(1-r) \\ 0 & 0 & 1 \end{bmatrix}.$$

Click here to view an animation of the following two examples.

*Examples.* Are the following dilations direct or indirect similarities?

 $P = \begin{pmatrix} 0 & 1 & -0.5 & 0 \\ 0 & 1 & 0.5 & 0 \\ 1 & 1 & 1 & 1 \end{pmatrix} Q = \begin{pmatrix} -2 & 0 & -3 & -2 \\ -0.3 & 1.7 & 0.7 & -0.3 \\ 1 & 1 & 1 & 1 \end{pmatrix}$  $A = \begin{bmatrix} 0 & 2 & -0.3 \\ 0 & 0 & 1 \end{bmatrix}$  $P_{1,i}$ 4 6  $Q = \begin{pmatrix} 6 & 4 & 7 & 6 \\ 0.9 & -1.1 & -0.1 & 0.9 \\ 1 & 1 & 1 & 1 \end{pmatrix}$ 0 1 0.5 0 -2 0.9 P = 0 |A| = 4P<sub>1,i</sub> Q<sub>1,i</sub> -2 4 6 -1

*Exercise 3.103.* Let C(-2, -3, 1), X(1, 3, 1), and X'(2, 5, 1). (a) Show the three points are collinear. (b) Find the matrix of a dilation with center *C* that maps X to X'. (c) Find the image of (-4, 7, 1) under this dilation. (d) Find the image of the line l[1, 1, 1] and m[1, 1, -1] under this dilation.

*Exercise 3.104.* Find a matrix of a similarity that maps *X*(1, 2, 1) to *X'*(2, 4, 1) and *Y*(0, 0, 1) to *Y'*(-4, 2, 1), then find the image of *Z*(3, 10, 1).

*Exercise 3.105.* Find a matrix of a similarity that maps *X*(0, 0, 1) to *X'*(5, 0, 1) and *Y*(1, 0, 1) to *Y'*(5, 8, 1), and *Z*(1, 1, 1) to *Z'*(-3, 0, 1), then find the image of *P*(4, -3, 1).

*Exercise 3.106.* Show a derivation for Proposition 3.16.

*Exercise 3.107.* Show a derivation for Proposition 3.17.

3.6.1 Similarity Transformations of the Euclidean
Plane
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